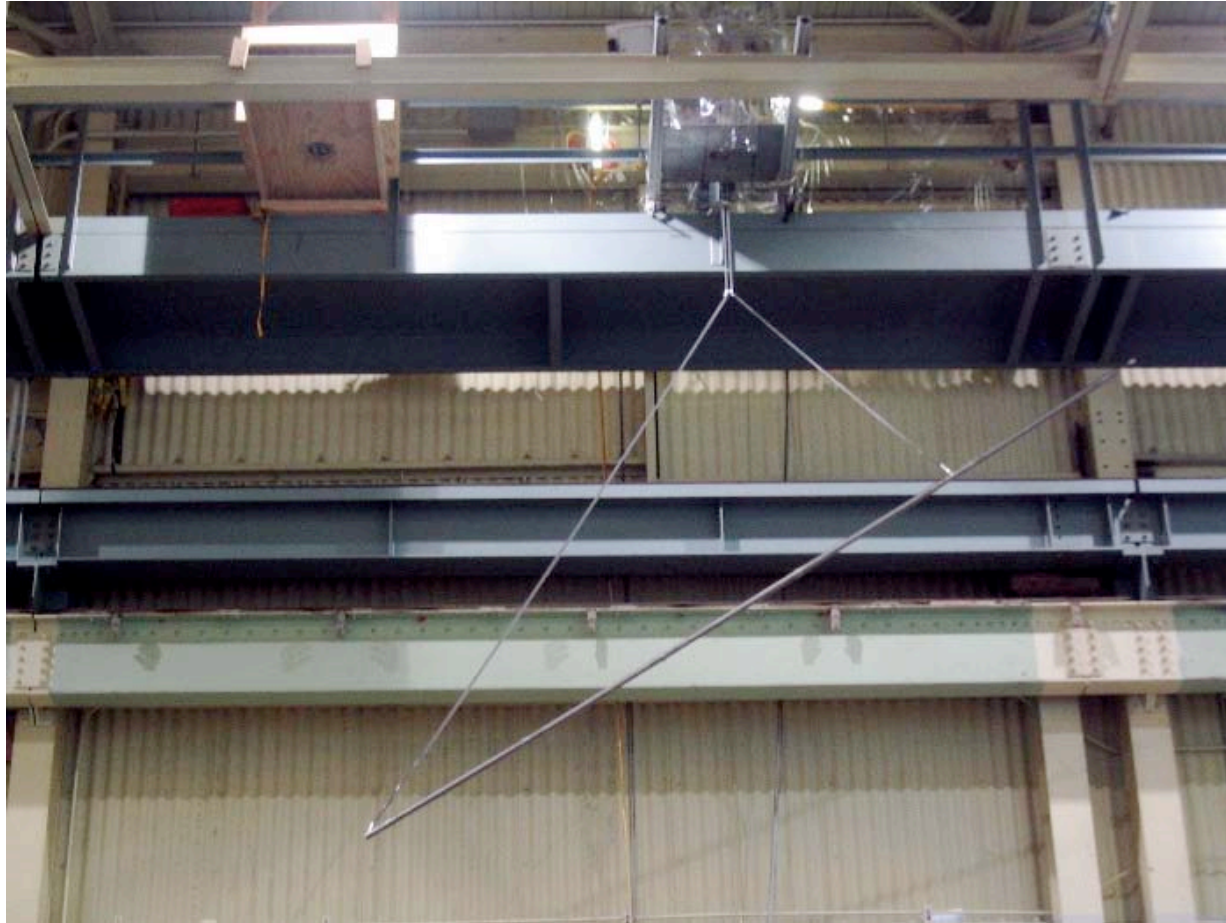


# Emergency Recovery Options for the 4pi System

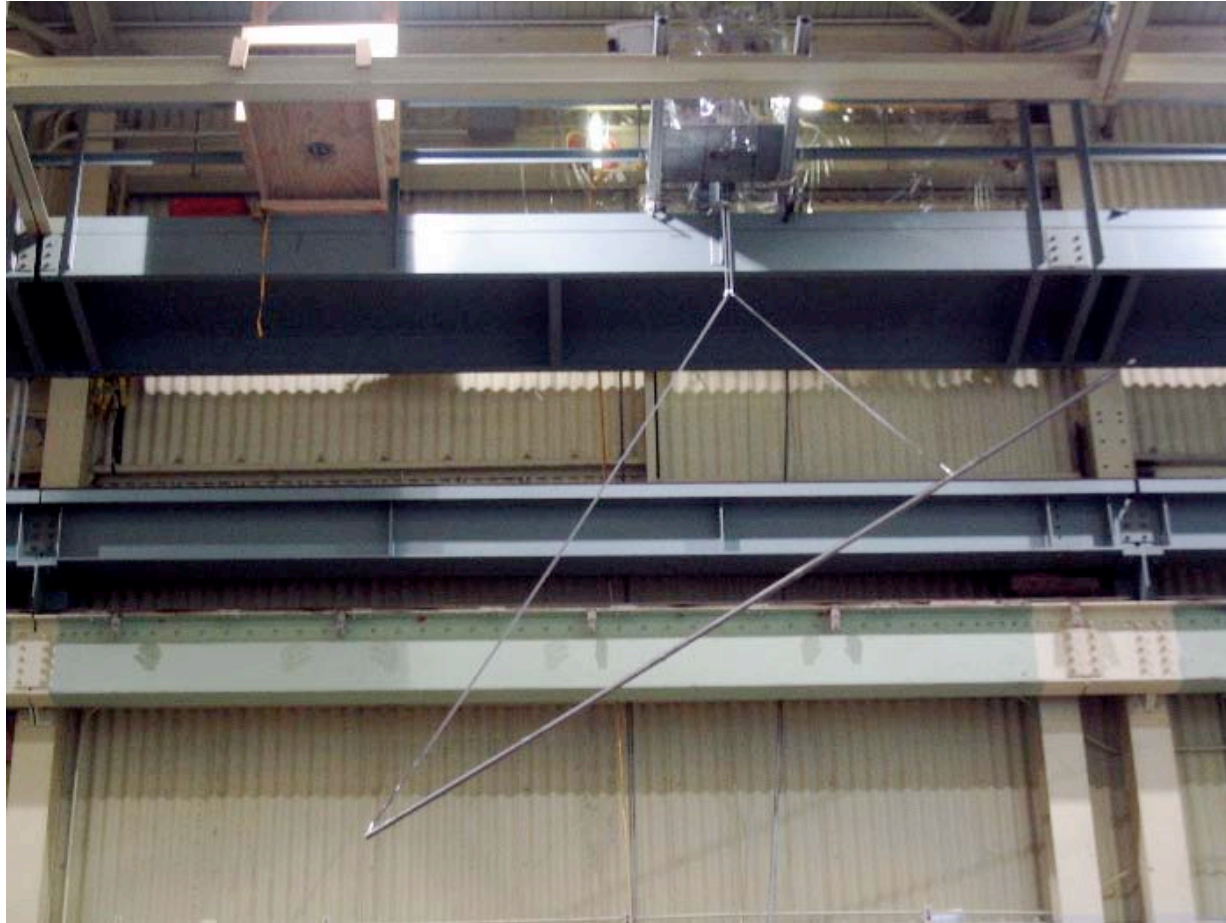
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How can we retract the system from any state in the detector?

# Emergency Recovery Options for the 4pi System

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Recovery may require raising or lowering of cables!

# Failure Modes and Actions

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## 1. Control Failures

### Power Outage

⇒ UPS ⇒ Computer and software recovery

### Computer Crash

⇒ restart computer ⇒ restart controls ⇒ read last position from database ⇒ move system back into neutral position ⇒ tare system

### Software Crash

⇒ restart controls ⇒ read last position from database ⇒ move system back into neutral position ⇒ tare system

*-> Fred demonstrated robustness of system yesterday.*

# Failure Modes and Actions

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## 2. Hardware Failures

### Instrumentation Unit

⇒ move system back into neutral position using cable length measurements ⇒ retract pole ⇒ exchange IU

### Motor 2 or GearBox 2 (lower spool)

- ⇒ secure system and think!
- ⇒ retract pole using motor 1 (normal retraction)
- ⇒ lower cable 2 as needed

### Motor 1 or GearBox 1 (upper spool)

- ⇒ secure system and think!
- option 1: ⇒ retract pole using motor 2 (inverted retraction)
- option 2: ⇒ manipulate both cables manually

# What do you need for emergency recovery?

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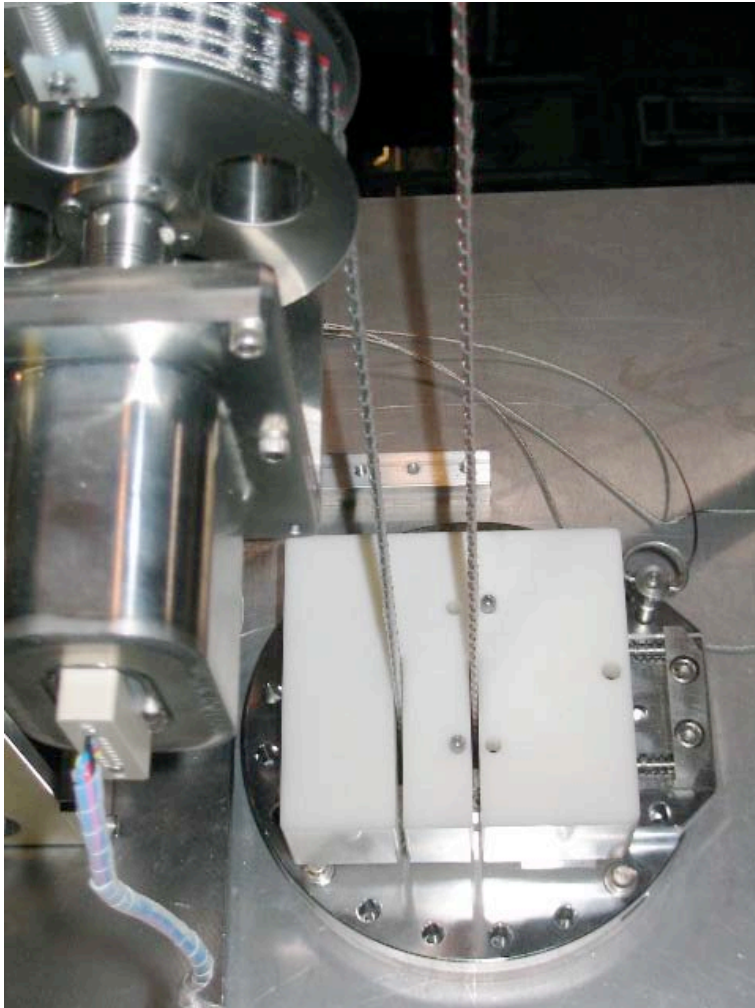
1. Securing the system with cable clamp ✓
2. Software simulation for pole position:  
what happens if I raise or lower this cable? ✓
3. Method to raise cable. ✓
4. Method to lower cable. ✓



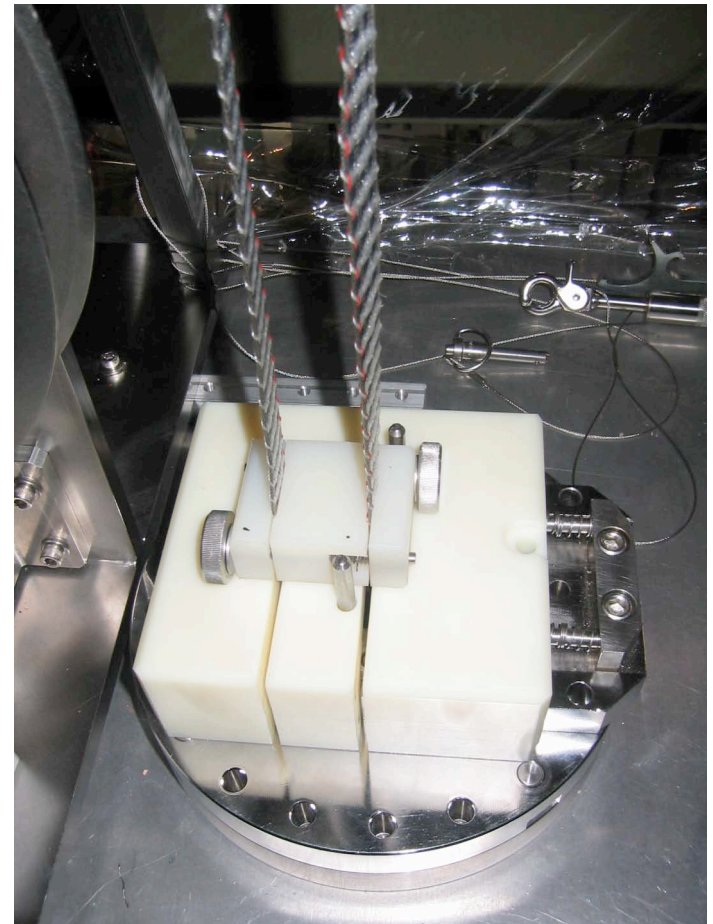
# Securing the System

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Normal Deployment



Emergency Locking Clamp



# Software Simulation of Pole Position in Manual Mode

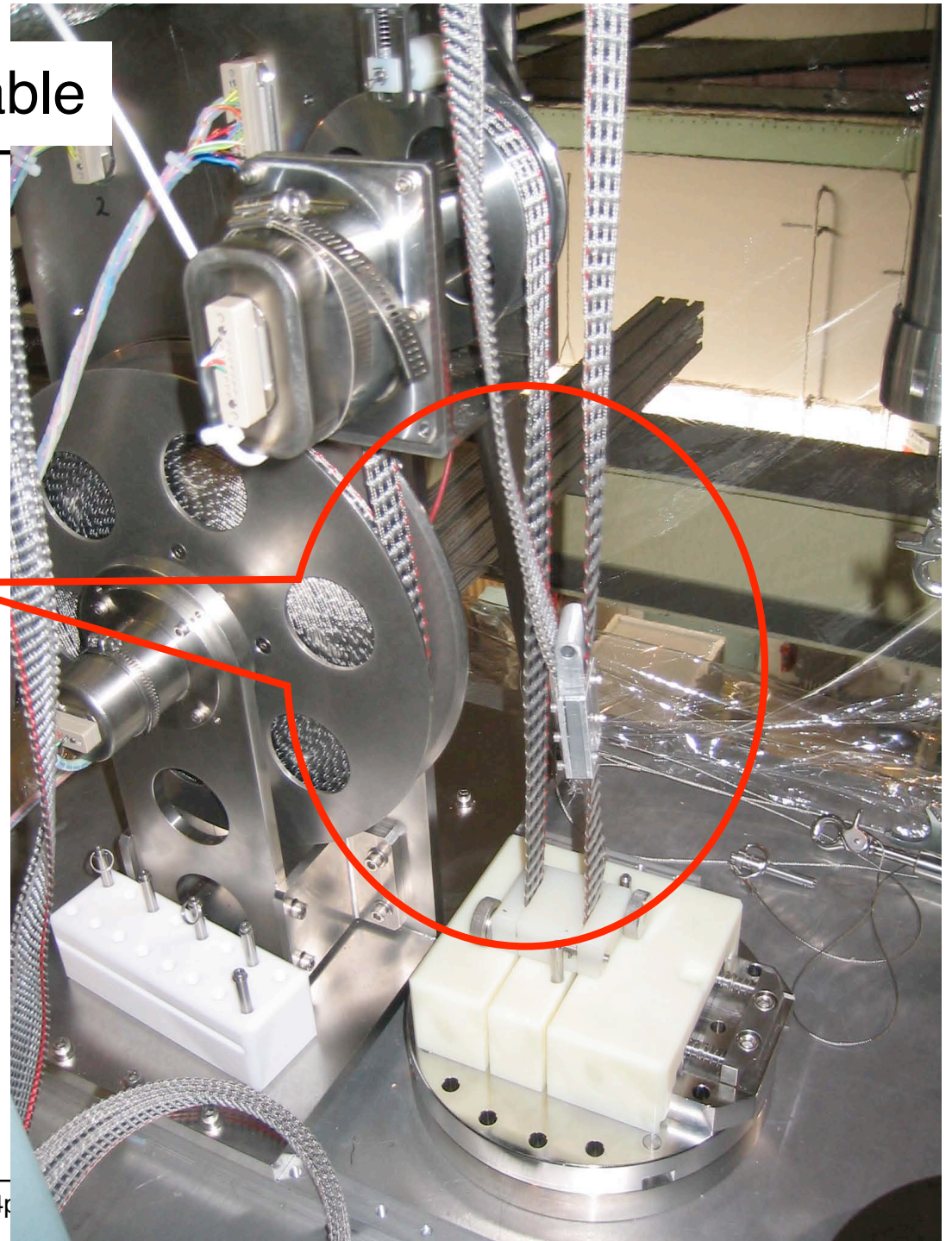
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- > Run control program in simulated mode. (in place)
- > Proceed in small steps.

## Method to Lower the Cable

Cannot unwind spools manually

Can use cable clamp to attach another cable





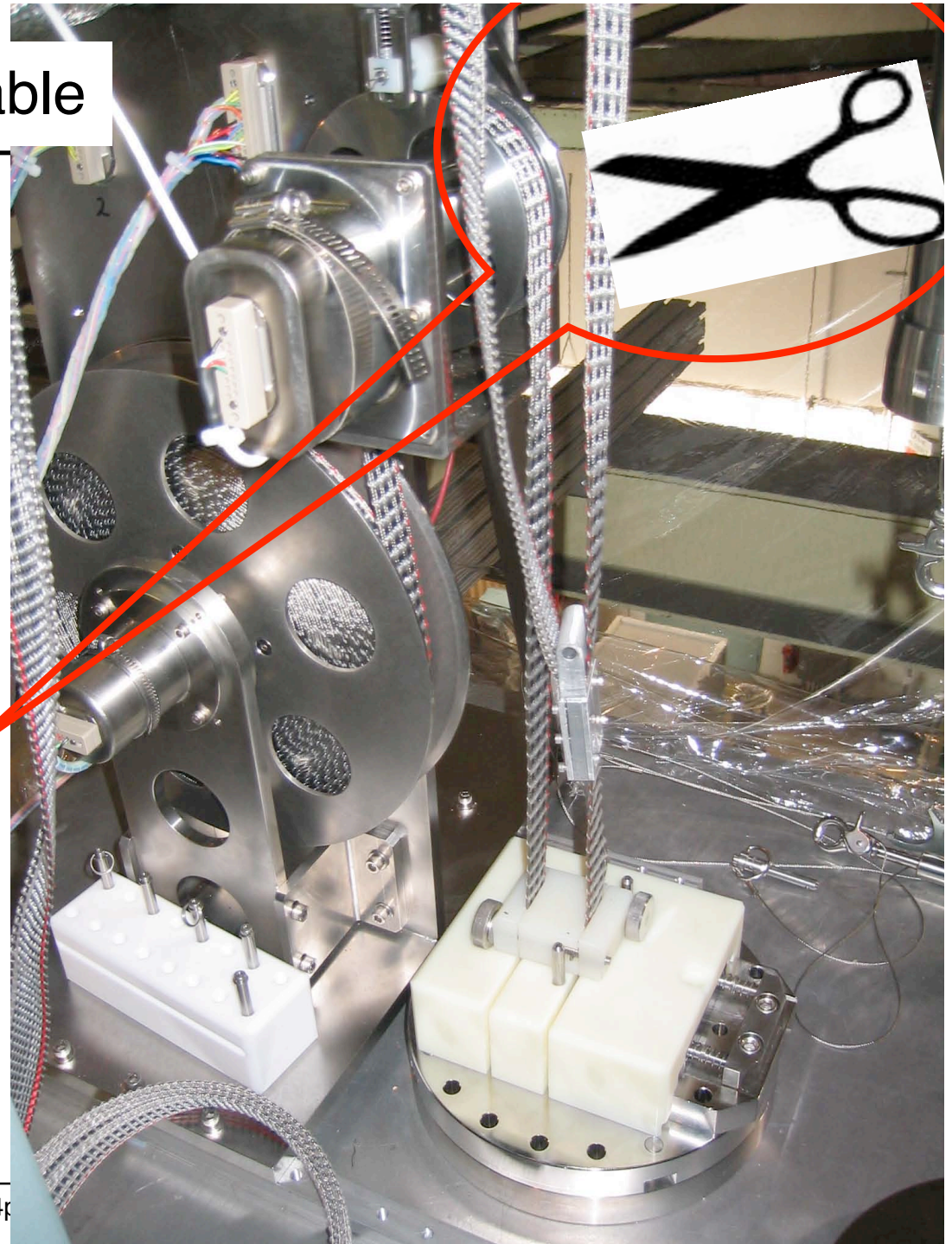
## Method to Lower the Cable

Cannot unwind spools manually

Can use cable clamp to attach another cable

Cut cable connected to spool

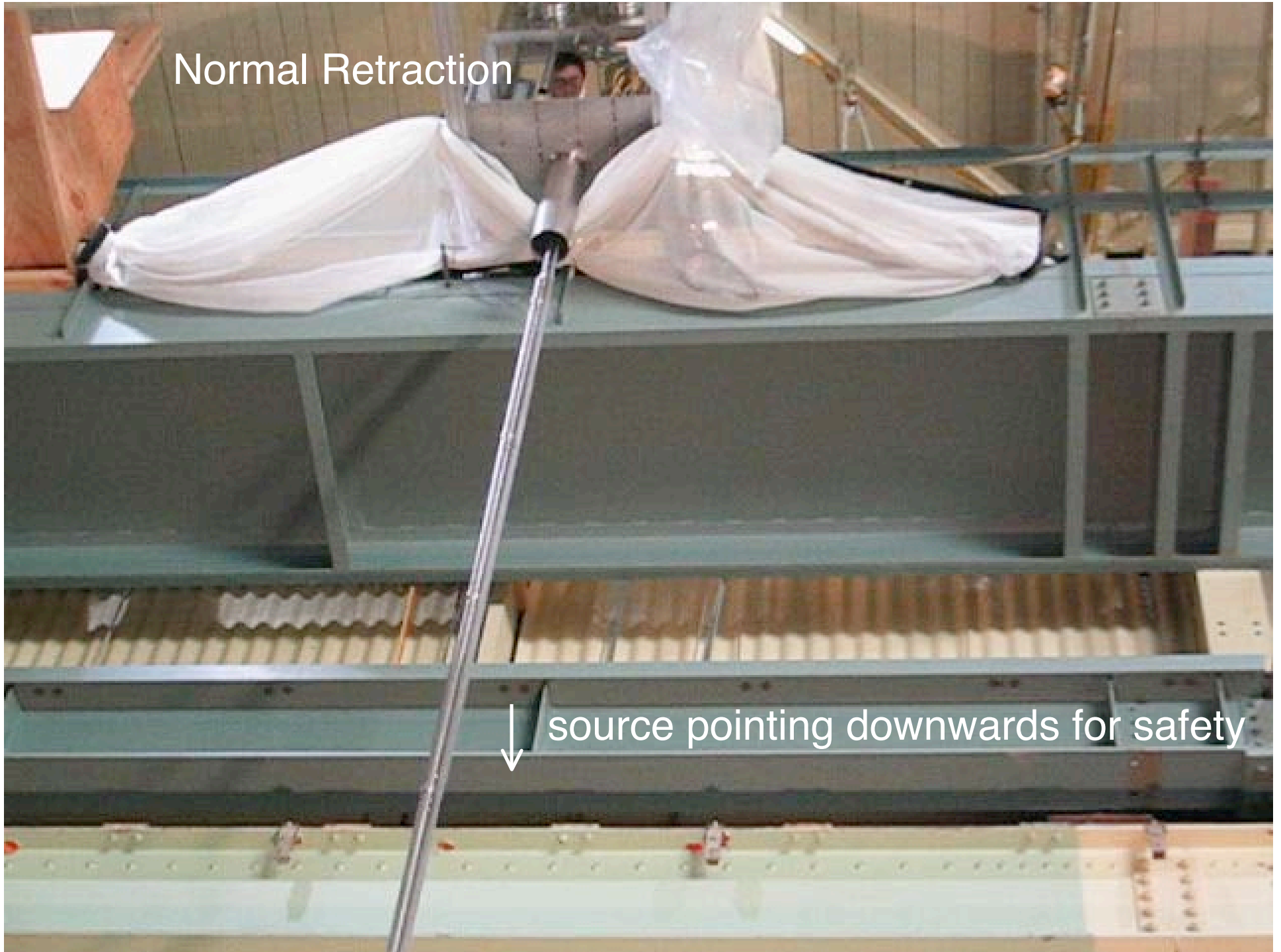
*-> Now we can manually lower cable.*



Normal Retraction

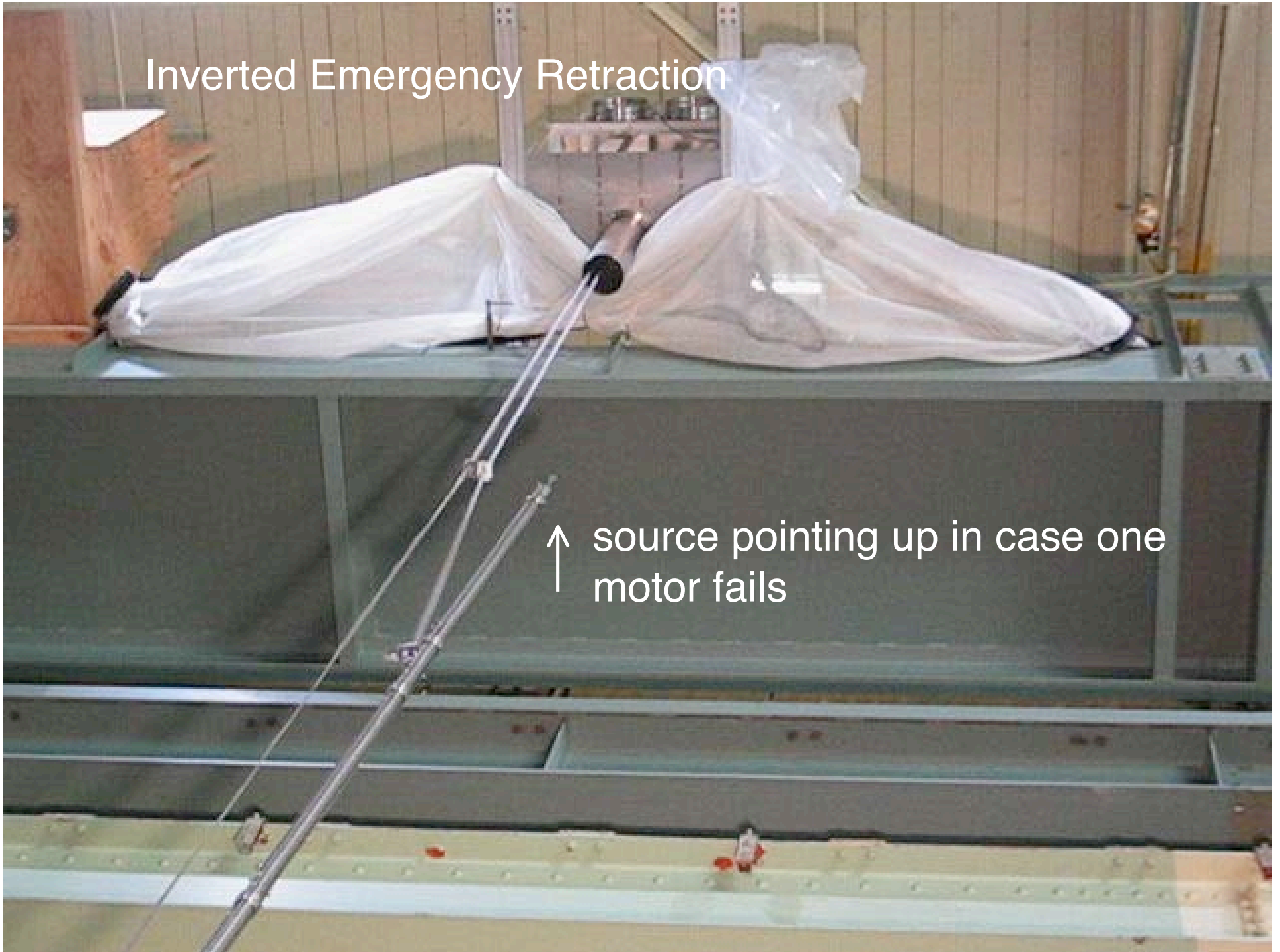


source pointing downwards for safety



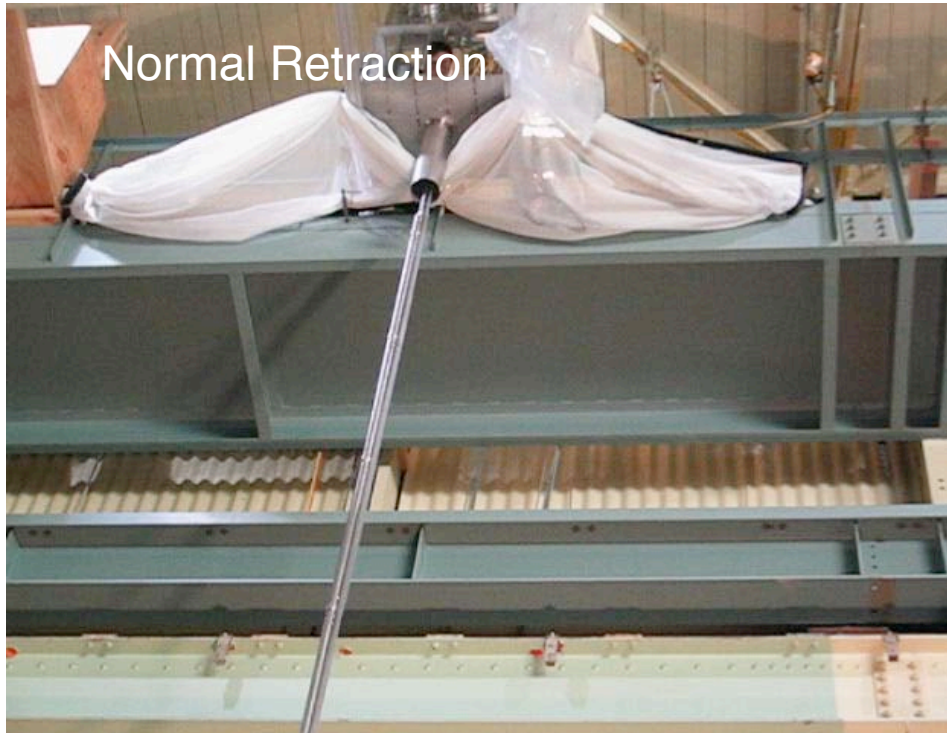
## Inverted Emergency Retraction

↑ source pointing up in case one motor fails

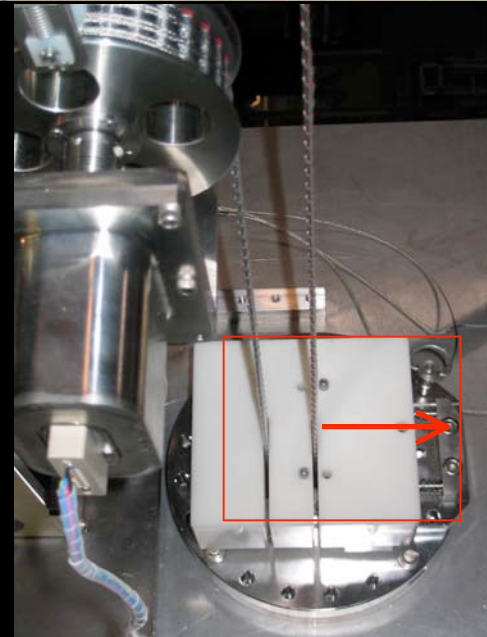
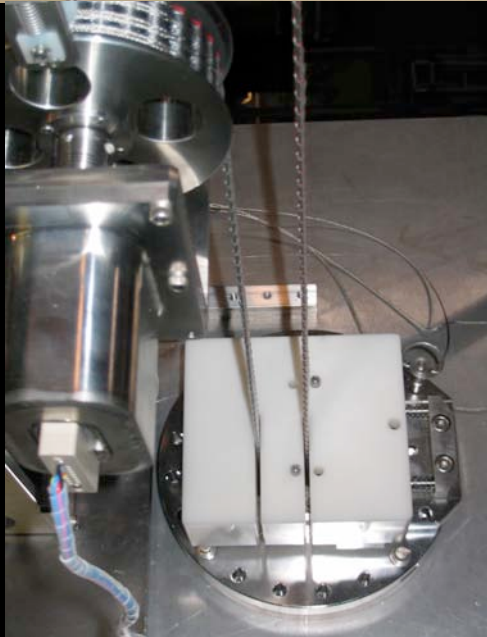




Normal Retraction

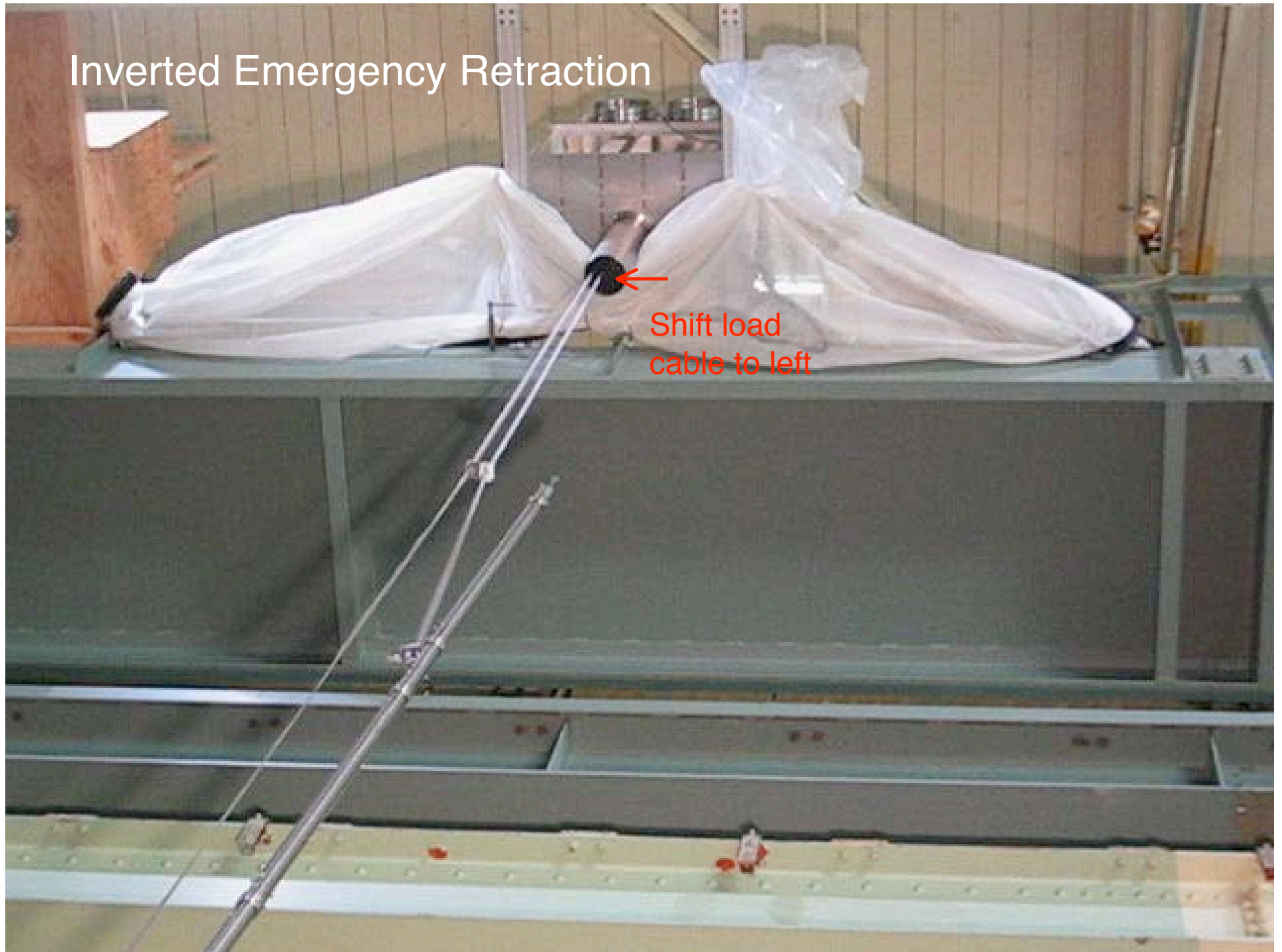


Inverted Retraction





# Inverted Emergency Retraction



## Inverted Retraction



# Summary

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- ✓ Easy recovery from power, software, or computer problems.
- ✓ Software runs on several platforms with Java.
- ✗ Cannot exchange motors or gears without opening penthouse.
- ✓ Have basic tools to manually raise or lower the cables.
- ✓ Have software to simulate steps of manual operation.

We may want to think about better tools for manual operation but...

*It is possible to manually retract the pole!*

# Suggestions & Comments

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- Prepare cable clamps to move cables down in steps for each cable.
- One cable mark should always be visible in the glovebox. Will mark spools to estimate cable lengths.

[Note: if we cut cable we will lose information from IU!]

- When we attach a secondary cable can we lower the cable far enough to get the system back into neutral position without jamming the pivot block? Make a figure showing that we can attach a long enough secondary cable to lower pole into neutral position.
- What about twisting of rope? Demonstrate that we can move pole into neutral position when cable is twisted.
- Does the cable push the pole out of the center position?